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|  | **AUVSI Robosub Competition**  **CSULB Team “Zeebo” Bio**  **Zeebo.org** |  |

The California State University, Long Beach underwater robotics program finds its roots in the aspirations of a small, tight knit group of computer engineering students who, in the summer of 2014, set out to develop the university’s first remote operated underwater vehicle, code named: “Xeebo”. Following a rapid prototyping phase and successful first deployment the team set their sights on a bigger fish, the AUVSI Robosub competition, where they would take the lessons learned developing a remotely operated vehicle to create its autonomous older brother “Zeebo”. They quickly recruited the best and brightest of their cohort to aid in development, pulling from all disciplines within the engineering department to bring greater refinement and capability to this aquatic automaton. Over the last ten months, the team has worked feverishly to bring Zeebo to life and to be able to hold its own as the “new guy” at the Robosub competition. Every member of the team making sacrifices of time, money, and hard work to bring this dream to life. Led by former United States Army Ranger, Sgt. Matthew Connolly, this focused and ambitious team now seeks to establish a precedent for their fellow students, their school, and the engineering field as a whole of commitment, ingenuity, hard work and perseverance in the hopes of making this world a better place where science and technology may thrive.